EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	0	position$4 near6 ((sens$4 measur$6 detect$4) and (calculat$4 comput$6 control$4) and actuat$4) near6 (input output signal) and (gravity gravitation$4) near6 (adjust$4 compensat$4 correct$4) near6 ((calculat$4 comput$6 control$4) and actuat$4) near6 (input output signal) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:32
L3	0	position$4 near6 ((sens$4 measur$6 detect$4) and (calculat$4 comput$6 control$4) and actuat$4) near6 (input output signal) and (gravity gravitation$4) near6 compensat$4 near6 ((calculat$4 comput$6 control$4) and actuat$4) near6 (input output signal) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:32
L4	0	(gravity gravitation$4) near6 compensat$4 near6 (force control$4 actuat$4) with (output signal input) near6 position$4 and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:33
L5	0	position$4 near3 ((sens$4 measur$6 detect$4) and (calculat$4 comput$6 control$4) and actuat$4) near3 (input output signal) and (gravity gravitation$4) near3 compensat$4 near3 ((calculat$4 comput$6 control$4) and actuat$4) near3 (input output signal) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:33

L6	0	(position location displac$6) near3 ((measur$6 sensor sensing detect$4) and (control$4 actuat$4)) with (gravity gravitational) near3 (compensat$4 force control $4 actuat$4) with (signal input output) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:34
L7	0	(position location displac$6) near3 ((measur$6 sensor sensing detect$4) and (control$4 actuat$4)) with (gravity gravitational) near3 (compensat$4 force control $4 actuat$4) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:34
L8	0	"33"/$ and (position location displac$6) near6 ((measur$6 sensor sensing detect$4) same (control$4 actuat$4)) and (gravity gravitational) near3 (compensat$4 force control$4 actuat$4) with (spring pulley tension motor) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:35
L9	3	"318"/$ and (position location displac$6) near6 ((measur$6 sensor sensing detect$4) same (control$4 actuat$4)) and (gravity gravitational) near3 (compensat$4 force control $4 actuat$4) with (spring pulley tension motor) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:35

L10	1	"700"/$ and (position location displac$6) near6 ((measur$6 sensor sensing detect$4) same (control$4 actuat$4)) and (gravity gravitational) near3 (compensat$4 force control $4 actuat$4) with (spring pulley tension motor) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:35
L11	0	"702"/$ and (position location displac$6) near6 ((measur$6 sensor sensing detect$4) same (control$4 actuat$4)) and (gravity gravitational) near3 (compensat$4 force control $4 actuat$4) with (spring pulley tension motor) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:37
L12	0	gravity near3 (compensat$4 control$4) with position near3 control$4 with (output input signal) with actuat$4 with gravit$6 near3 force and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:40
L13	0	gravity near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 same gravit$6 near3 force and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:40
L14	0	gravit$6 near3 (compensat $4 control$4) same position near3 control$4 same (output input signal) same actuat$4 same gravit$6 near3 force and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:40

L15	0	gravit$6 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 same force and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:41
L16	0	gravit$6 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:41
L17	0	gravit$6 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:41
L18	0	gravit$8 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 same gravit$8 near3 force and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:42
L19	0	gravit$8 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 same force and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:42
L20	0	gravit$8 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) and (@ad<"20030807" @rlad<"20030807") and @pd>"20080601"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:43

L21	3	gravit$8 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 same gravit$8 near3 force and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:43
L22	12	gravit$8 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 same force and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:52
L23	19	gravit$8 near3 (compensat$4 control$4) same position near3 control$4 same (output input signal) same actuat$4 and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:52
L24	2	gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output input signal) with actuat$4 and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:58
L25	35	gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output input signal) and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:58
L26	2	"33"/$ and gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output input signal) and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:58
L27	6	"318"/$ and gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output input signal) and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:58
L28	0	"700"/$ and gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output input signal) and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:58

L29	0	"702"/$ and gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output input signal) and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 18:59
L30	0	gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output and input) near signal and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 19:01
L31	1	gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output and input) and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 19:01
L32	3	gravit$8 near3 (compensat$4 control$4) with position near3 control$4 with (output and input)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/11/25 19:03

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